

TRAVIS DRIVER

🏠 Atlanta, GA 30324 • 📞 (972) 310-0047
✉️ travisdriver@gatech.edu • 🌐 travisdriver.github.io

EDUCATION

Georgia Institute of Technology August 2019 - Present
Doctor of Philosophy, Robotics GPA: 4.00/4
Advisor: Professor Panagiotis Tsiotras

Georgia Institute of Technology May 2022
Master of Science, Aerospace Engineering GPA: 4.00/4

The University of Texas at Austin May 2019
Bachelor of Science, Computational Engineering, High Honors GPA: 3.93/4

RESEARCH EXPERIENCE

Dynamics and Control Systems Lab (DCSL) August 2019 - Present
Graduate Research Assistant Atlanta, GA
· Conducting research in computer vision, 3D perception, and navigation for proximity operations in space.

NASA Goddard Space Flight Center June 2022 - September 2022
Visiting Technologist Greenbelt, MD
· Developed novel feature detection and description methods for small body relative navigation.

Nonlinear Estimation and Autonomy Research (NEAR) Group September 2018 - May 2019
Undergraduate Research Assistant Austin, TX
· Implemented feature detection and tracking algorithms for autonomous spacecraft rendezvous.

Texas Spacecraft Lab June 2017 - January 2018
Algorithms Team Lead (Sept. 2017 - Jan. 2018), Systems Engineer (June 2017 - Sept. 2017) Austin, TX
· Led team of 5+ engineers to implement machine learning and computer vision algorithms to track target spacecraft for the Seeker mission.
· Designed, integrated, and tested the GUI used to monitor real-time electrical power systems data in orbit for the ARMADILLO mission

Institute for Computational Engineering and Sciences May 2017 - August 2017
Undergraduate Research Assistant Austin, TX
· Implemented and evaluated novel clustering methods for a stochastic Monte Carlo optimization, sampling, and integration software library.

INDUSTRY EXPERIENCE

Sandia National Laboratories June 2019 - August 2019
Software R&D Intern Albuquerque, NM
· Implemented feature-based visual-SLAM algorithms for GPS-denied autonomous drone navigation.
· Applied deep learning techniques for robust and efficient object detection in X-ray images.

Northrop Grumman January 2018 - August 2018
Guidance, Navigation & Control Engineer Intern Wallops Island, VA
· Implemented novel Inertial Navigation System (INS) calibration methods improving navigation performance by ~43%.
· Designed software interface to configure the on-board Flash memory of the Attitude Control System.

TEACHING EXPERIENCE

COE 301: Introduction to Computer Programming







August 2017 - December 2017

Teaching Assistant, *The University of Texas at Austin*

Austin, TX

- Aided in teaching core programming concepts in MATLAB, C++, and Fortran to a class of 100+ engineering students.

PUBLICATIONS

1. [T. Driver](#) and P. Tsiotras. Efficient Feature Description for Small Body Relative Navigation using Binary Convolutional Neural Networks. In *AAS Guidance, Navigation and Control (GN&C) Conf.*, Breckenridge, CO, USA, February 2023. [Accepted] 
2. [T. Driver*](#), K. Tomita*, K. Ho, and P. Tsiotras. Deep Monocular Hazard Detection for Safe Small Body Landing. In *AAS/AIAA Space Flight Mechanics Meeting*, Austin, TX, USA, January 2023. *These authors contributed equally to this work. [Accepted] 
3. M. Dor, [T. Driver](#), K. Getzandanner, and P. Tsiotras. AstroSLAM: Autonomous Monocular Navigation in the Vicinity of a Celestial Small Body — Theory and Experiments. *Int. J. of Robotics Research*, 2022. [Under Review] [Preprint]
4. [T. Driver](#), K. Skinner, M. Dor, and P. Tsiotras. AstroVision: Towards Autonomous Feature Detection and Description for Missions to Small Bodies Using Deep Learning. *Special Issue on AI for Space, Acta Astronautica*, 2022. [Accepted]  
5. M. Dor, K. Skinner, [T. Driver](#), and P. Tsiotras. Visual SLAM for Asteroid Relative Navigation. In *IEEE Conf. on Computer Vision and Pattern Recognition (CVPR)*, 1st Workshop on AI for Space, Virtual, June 2021. 
6. [T. Driver](#), M. Dor, K. Skinner, and P. Tsiotras. Space Carving in Space: A Visual SLAM Approach to 3D Shape Reconstruction of a Small Celestial Body. In *AAS/AIAA Astrodynamics Specialist Conf.*, Lake Tahoe, CA, USA, August 2020. 

HONORS & AWARDS

NASA Space Technology Graduate Research Fellowship, *NASA* (2021 - Present)

President's Fellowship, *Georgia Institute of Technology* (2019 - Present)

University Honors, *The University of Texas at Austin* (2015 - 2019)

SKILLS

Programming: C++, C, Python, MATLAB, C#, Fortran, Bash, Java

Software: GTSAM, ROS, OpenCV, PyTorch, Tensorflow, Blender, SolidWorks

Certifications: Technician Class Operator Radio License, NASA GSFC Electrostatic Discharge Operator